

Q1 Solution

$$\delta U = 0$$

$$P\delta x - k(2l - 2l \cos\theta)\delta y = 0$$

$$x = l \sin\theta, \quad \delta x = l \cos\theta \delta\theta$$

$y = 2l - 2l \cos\theta$ (measured from wheel position when spring is unstretched)

$$\delta y = 2l \sin\theta \delta\theta$$

$$\text{So } P(l \cos\theta \delta\theta) - k(2l - 2l \cos\theta)(2l \sin\theta \delta\theta) = 0$$

$$P = \frac{4kl (\sin\theta - \sin\theta \cos\theta)}{\cos\theta}$$

$$\text{or } P = 4kl(\tan\theta - \sin\theta)$$

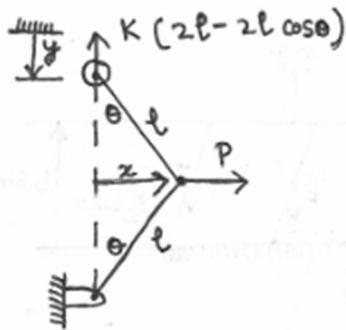


Fig 1

Q2 Solution

$$x = \text{spring compression} = \frac{h}{\cos\theta} - h = h(\sec\theta - 1)$$

$$\delta U = \delta V_e; P\delta s = \delta \left(\frac{1}{2} kx^2 \right) = kx \delta x$$

$s = h \tan\theta$ so that

$$P\delta(h \tan\theta) = kh^2(\sec\theta - 1)\sec\theta \tan\theta \delta\theta$$

$$Ph \sec^2\theta \delta\theta = kh^2(\sec\theta - 1)\sec^2\theta \sin\theta \delta\theta$$

$$P = kh(\sec\theta - 1)\sin\theta$$

$$\text{or } P = kh \tan\theta(1 - \cos\theta)$$

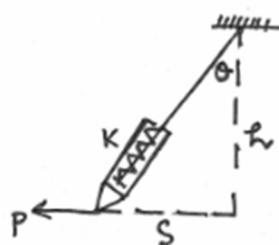


Fig 2

Q3 Solution

$$\delta U = 0: 2C \delta(a \cos \theta) + mg \delta(2a \sin \theta) = 0$$

$$-2Ca \sin \theta \delta \theta + 2mga \cos \theta \delta \theta = 0$$

$$C = mg \cot \theta$$

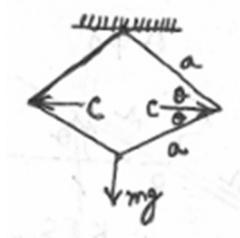


Fig 3

Q4 Solution

$$\tan \phi = 0.30, \quad \phi = 16.70^\circ$$

$$\tan \alpha = \tan 5^\circ = 0.0875$$

$$\sum F_x = 0: P = R \sin(\phi + \alpha)$$

$$\sum F_y = 0: W = R \cos(\phi + \alpha)$$

$$\tan(\phi + \alpha) = \frac{P}{W}$$

work input : $P\delta x$

Work output : $W\delta y$ where $\delta y = \delta x \tan \alpha$

$$e = \frac{W \delta y}{P \delta x} = \frac{\tan \alpha}{\tan(\phi + \alpha)} = \frac{\tan 5^\circ}{\tan(16.70^\circ + 5^\circ)} = 0.220$$

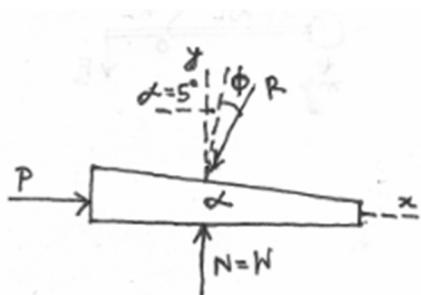


Fig 4

Q5 Solution

$$x_C = (0.4 \text{ m}) \sin \theta$$

$$\delta x_C = 0.4 \cos \theta \delta \theta$$

$$y_A = (0.2 \text{ m}) \cos \theta$$

$$\delta y_A = -0.2 \sin \theta \delta \theta$$

Spring:

Unstretched length = 0.2 m

$$F = k(0.2 \text{ m} - y_A) = k(0.2 - 0.2 \cos \theta)$$

$$= (300 \text{ N/m})(0.2)(1 - \cos \theta)$$

$$F = 600(1 - \cos \theta)$$

Virtual Work:

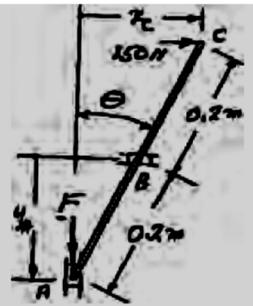
$$\delta U = 0: (150 \text{ N})\delta x_C + F\delta y_A = 0$$

$$150(0.4 \cos \theta \delta \theta) + 600(1 - \cos \theta)(-0.2 \sin \theta \delta \theta) = 0$$

$$\frac{150(0.4)}{600(0.2)} = \frac{1}{2}: \quad \frac{1}{2} = (1 - \cos \theta) \tan \theta$$

Solve by trial and error:

$$\theta = 52.2^\circ$$



Q6 Solution

$$V_g = 2mgl \cos \frac{\beta}{2} + K\beta, \quad \frac{dV}{d\beta} = 0 \quad \text{for } \beta = 0$$

$$\frac{d^2V}{d\beta^2} = -\frac{1}{2}mgl \cos \frac{\beta}{2} + K$$

$$= -\frac{1}{2}mgl + K \text{ for } \beta = 0$$

$$= (+) \text{ stable if } K > \frac{1}{2}mgl$$

$$\text{Thus } K_{min} = \frac{1}{2}mgl$$

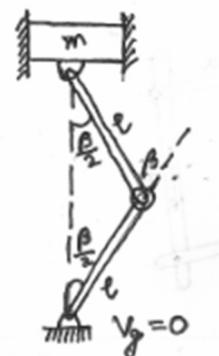


Fig 6

Q7 Solution

$$m_1 = 80 \text{ kg} \quad m_2 = 10 \text{ kg} \quad b = 600 \text{ mm}$$

$$\delta U = 0: -F\delta(b \cos\theta) - m_1 g \delta(b \sin\theta) - 3m_2 g \delta\left(\frac{b}{2} \sin\theta\right) = 0$$

$$Fb \sin\theta \delta\theta - m_1 g b \cos\theta \delta\theta + \frac{3}{2} m_2 g b \cos\theta \delta\theta$$

$$F = g \cot\theta \left(m_1 + \frac{3}{2} m_2\right) = 9.81 \left(80 + \frac{3}{2} \times 10\right) \cot\theta = 932 \cot\theta \text{ N}$$

Solution by force and moment equilibrium would require dismemberment with four FBD's and eventual elimination of unwanted forces and dimensions.

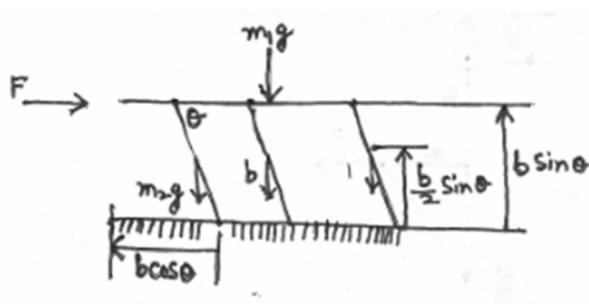


Fig 7

Q8 Solution

$$\delta U = 0;$$

$$P\delta(2a \sin\theta) + mg \delta(2a \cos\theta) + 3mg\delta(a \cos\theta) = 0$$

$$2Pa \cos\theta \delta\theta = 5mga \sin\theta \delta\theta$$

$$P = \frac{5}{2}mg \tan\theta$$

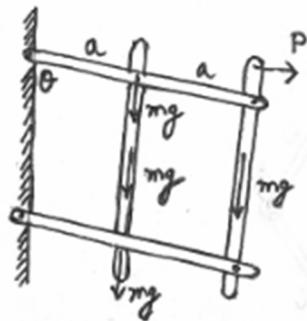


Fig 8

Q9 Solution

$$\delta V_e = kx \delta x \text{ where } x = s - b = \sqrt{b^2 + u^2} - b$$

$$\delta x = \frac{u \delta x}{\sqrt{b^2 + u^2}}$$

$$\delta U' = \delta V_e; P \delta u = k \left(\sqrt{b^2 + u^2} - b \right) \frac{u \delta u}{\sqrt{b^2 + u^2}}$$

$$P = \left(1 - \frac{b}{\sqrt{b^2 + u^2}} \right) ku$$

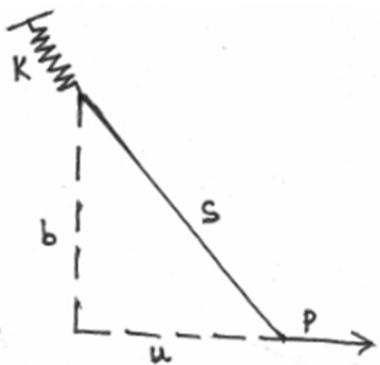


Fig 9

Q10 Solution

$$FBD @ \theta = 0: \sum M_o = 0:$$

$$mg(1-n)L - F_s(nL) = 0$$

$$F_s = \frac{mg(1-n)}{n} = k\delta_{st}$$

$$\delta_{st} = \frac{mg(1-n)}{nk}$$

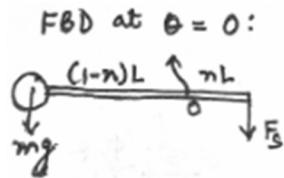


Fig 10a

$\theta \neq 0$:

$$V = V_g + V_c$$

$$= -mg[(1-n)L \sin\theta] + \frac{1}{2k} \left[\frac{mg(1-n)}{kn} + nL \sin\theta \right]^2$$

$$= \frac{m^2 g^2 (1-n)^2}{2kn^2} + \frac{n^2 L^2 k \sin^2 \theta}{2}$$

$$\frac{dV}{d\theta} = n^2 L^2 k \sin\theta \cos\theta = 0 \text{ at } \theta = 0$$

$$\frac{d^2V}{d\theta^2} = n^2 L^2 k (\cos^2 \theta - \sin^2 \theta) > 0 \text{ at } \theta = 0 \text{ for all } 0 < n < 1$$

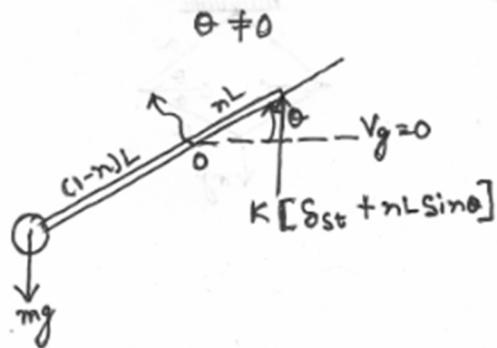


Fig 10b